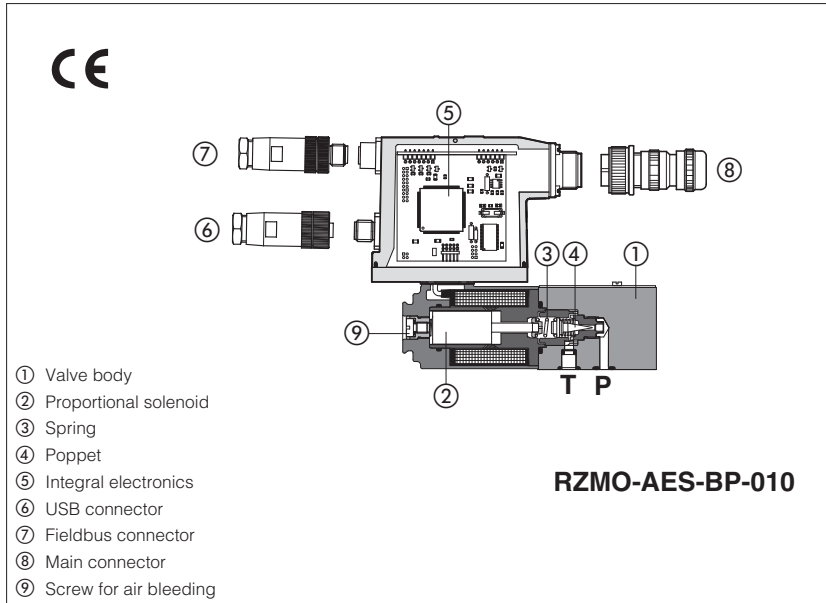


# Proportional relief valves

digital, direct operated, open loop



## RZMO-A, RZMO-AEB, RZMO-AES

Poppet type direct operated digital proportional relief valves for pressure open loop controls.

Executions:

- **A** without integral driver, to be coupled with separated driver section ②
- **AEB** with basic integral digital electronic driver, analog reference signals and USB port for software functional parameters setting
- **AES** with full integral digital electronic driver and fieldbus interface for functional parameters setting, reference signals and real-time diagnostics

The integral digital electronic driver performs the valve's hydraulic regulation according to the reference signal and assures valve-to-valve interchangeability thanks to the factory presetting

Size: **06**  
 Max flow: **4 l/min**  
 Max pressure: **350 bar**

### 1 MODEL CODE

<b>RZMO</b>	-	<b>A</b>	<b>EB</b>	-	<b>NP</b>	-	<b>010</b>	/	<b>315</b>	/	<b>*</b>	<b>**</b>	/	<b>*</b>
Proportional pressure relief valve size 06		A = open loop pressure control		EB = basic integral driver		ES = full integral driver						Seals material, see sect. ④, ⑤: - = NBR PE = FKM BT = HNBR		Series number
Fieldbus interfaces - USB port always present (1): NP = Not present      BP = PROFIBUS DP BC = CANopen          EH = EtherCAT		- = omit for execution with separated driver see section ②										Coil voltage only for -A - see section ④: - = standard coil for 24V <sub>DC</sub> Atos drivers 6 = optional coil for 12V <sub>DC</sub> Atos drivers 18 = optional coil for low current drivers		
Configuration: 010 = regulation on port P, discharge in T (direct operated version)												Electronics options only for AEB and AES - see section ④: I = current reference input 4 ÷ 20 mA (omit for standard voltage reference input 0 ÷ 10 V) Q = enable signal Z = double power supply, enable and fault signal - 12 pin connector		
												Max regulated pressure: 50 = 50 bar                      315 = 315 bar 100 = 100 bar                  350 = 350 bar 210 = 210 bar		

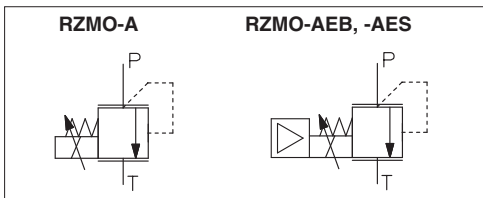
(1) AEB available only in version NP; AES available only in version BC, BP, EH

### 2 ELECTRONIC DRIVERS

Valve model	A							AEB	AES
Drivers model	E-MI-AC-01F	E-BM-AC-01F	E-ME-AC-01F	E-RP-AC-01F	E-MI-AS-IR	E-BM-AS-PS	E-BM-AES	E-RI-AEB	E-RI-AES
Type	Analog				Digital				
Format	plug-in to solenoid	DIN 43700 UNDECAL	EUROCARD	sealed and rugged box	plug-in to solenoid	DIN-rail panel		Integral to valve	
Data sheet	G010	G025	G035	G100	G020	G030	GS050	GS115	

Note: for main and communication connector see sections ⑪, ⑫

## Hydraulic symbol



## 3 GENERAL NOTES

RZMO-A\* proportional valves are CE marked according to the applicable Directives (e.g. Immunity/Emission EMC Directive and Low Voltage Directive).

Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in table F003 and in the installation notes supplied with relevant components.

## 4 FIELDBUS - only for AES

Fieldbus allows the direct communication of the proportional valve with machine control unit for digital reference signal, diagnostics and settings of functional parameters. Analog reference signal remain available on the main connector for quick commissioning and maintenance. For detailed information about fieldbus features and specification see tech table **GS510**.

## 5 MAIN CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Assembly position	Any position			
Subplate surface finishing	Roughness index, Ra 0,4 flatness ratio 0,01/100 (ISO 1101)			
MTTFd valves according to EN ISO 13849	150 years, see technical table P007			
Ambient temperature range	<b>A:</b> standard = -20°C ÷ +70°C,		<b>/BT</b> option = -40°C ÷ +60°C	
	<b>AEB, AES:</b> standard = -20°C ÷ +60°C,		<b>/BT</b> option = -40°C ÷ +60°C	
Storage temperature range	<b>A:</b> standard = -20°C ÷ +80°C,		<b>/BT</b> option = -40°C ÷ +70°C	
	<b>AEB, AES:</b> standard = -20°C ÷ +70°C,		<b>/BT</b> option = -40°C ÷ +70°C	
Coil resistance R at 20°C	Standard = 3 ÷ 3,3 Ω	Option /6 = 2 ÷ 2,6 Ω	Option /18 = 13 ÷ 13,4 Ω	
Max. solenoid current	Standard = 2,6 A	Option /6 = 3,25 A	Option /18 = 1,5 A	
Max. power	<b>A</b> = 30 Watt <b>AEB, AES</b> = 50 Watt			
Insulation class	H (180°) Due to the occurring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account			
Protection degree to DIN EN60529	IP66/67 with mating connectors			
Tropicalization (only AEB, AES)	Tropical coating on electronics PCB			
Duty factor	Continuous rating (ED=100%)			
EMC, climate and mechanical load	See technical table G004			
Communication interface (only AEB, AES)	USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT IEC 61158
Communication physical layer (only AEB, AES)	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX

Max regulated pressure	[bar]	<b>50</b>	<b>100</b>	<b>210</b>	<b>315</b>	<b>350</b>
Min. regulated pressure	[bar]	see Min. pressure / Flow diagrams at sect. 7				
Max. pressure at port P	[bar]	350				
Max. pressure at port T	[bar]	210				
Max. flow	[l/min]	4				
Response time 0-100% step signal (1)	[ms]	≤ 70				
(depending on installation)						
Hysteresis	[% of the max pressure]	≤ 1,5				
Linearity	[% of the max pressure]	≤ 3				
Repeatability	[% of the max pressure]	≤ 2				

**Notes:** above performance data refer to valves coupled with Atos electronic drivers, see section 2

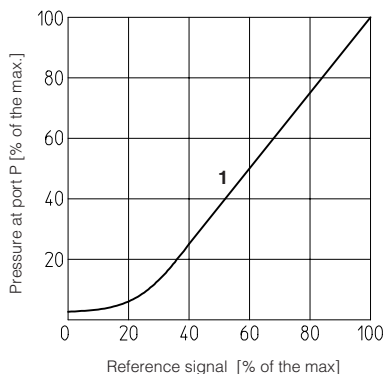
(1) Average response time value; the pressure variation in consequence of a modification of the reference input signal to the valve is affected by the stiffness of the hydraulic circuit: greater is the stiffness of the circuit, faster is the dynamic response.

## 6 SEALS AND HYDRAULIC FLUID - for other fluids not included in below table, consult our technical office

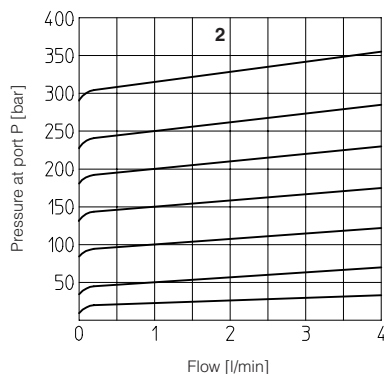
Seals, recommended fluid temperature	NBR seals (standard) = -20°C ÷ +60°C, with HFC hydraulic fluids = -20°C ÷ +50°C FKM seals (/PE option) = -20°C ÷ +80°C HNBR seals (/BT option) = -40°C ÷ +60°C, with HFC hydraulic fluids = -40°C ÷ +50°C		
Recommended viscosity	20 ÷ 100 mm <sup>2</sup> /s - max allowed range 15 ÷ 380 mm <sup>2</sup> /s		
Fluid contamination class	ISO 4406 class 20/18/15 NAS 1638 class 9, achievable with in line filter - 10 μm (β10 ≥ 75 recommended)		
<b>Hydraulic fluid</b>	<b>Suitable seals type</b>	<b>Classification</b>	<b>Ref. Standard</b>
Mineral oils	NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524
Flame resistant without water	FKM	HFJU, HFDR	ISO 12922
Flame resistant with water	NBR, HNBR	HFC	

**7 DIAGRAMS** (based on mineral oil ISO VG 46 at 50 °C)

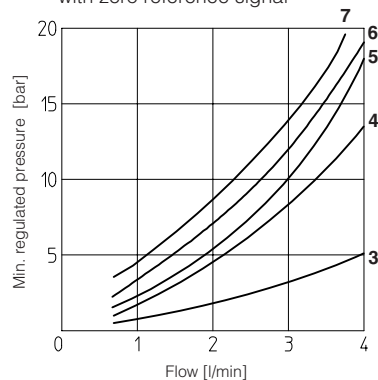
**1 Regulation diagrams**  
with flow rate Q = 1 l/min



**2 Pressure/flow diagrams**  
with reference signal set at Q = 1 l/min



**3-6 Min. pressure/flow diagrams**  
with zero reference signal



**3** = RZMO/50      **4** = RZMO/100  
**5** = RZMO/210    **6** = RZMO/315  
**7** = RZMO/350

**Note:**

The presence of counter pressure at port T can affect the pressure regulation and the minimum pressure.

**8 OPTIONS for -A**

**8.1 Coil voltage**

**Option /6** optional coil to be used with Atos drivers with power supply 12 Vdc

**Option /18** optional coil to be used with electronic drivers not supplied by Atos

**9 ELECTRONIC OPTIONS - for AEB and AES**

Standard driver execution provides on the 7 pin main connector:

**Power supply** - 24Vdc must be appropriately stabilized or rectified and filtered; a 2.5 A fuse time lag is required in series to each driver power supply. Apply at least a 10000 µF/40 V capacitance to single phase rectifiers or a 4700 µF/40 V capacitance to three phase rectifiers

**Reference input signal** - analog differential input with 0÷+10 Vdc nominal range (pin D,E), proportional to desired valve pressure regulation

**Monitor output signal** - analog output signal proportional to the actual valve pressure regulation = 0÷+10 Vdc nominal range

**Note:** a minimum booting time of 500 ms has been considered from the driver energizing with the 24 VDC power supply before the valve has been ready to operate. During this time the current to the valve coils is switched to zero.

**9.1 Option /I**

It provides 4 ÷ 20 mA current reference signal, instead of the standard ±10 V.

Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 V or ±20 mA.

It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage

**9.2 Option /Q**

It provides the possibility to enable or disable the valve functioning without cutting the power supply (the valve functioning is disabled but the driver current output stage is still active). To enable the driver supply a 24 VDC on the enable input signal

**9.3 Option /Z**

It provides, on the 12 pin main connector, the following additional features:

**Enable Input Signal**

To enable the driver, supply 24 VDC on pin 3 referred to pin 2: when the Enable signal is set to zero the valve functioning is disabled (zero current to the solenoid) but the driver current output stage is still active.

**Fault Output Signal**

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4÷20mA input, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC (pin 11 referred to pin 2): Fault status is not affected by the Enable input signal

**Power supply for driver's logics and communication**

Separated power supply for the solenoid (pin 1, 2) and for the digital electronic circuits (pin 9, 10).

Cutting solenoid power supply allows to interrupt the valve functioning but keeping energized the digital electronics thus avoiding fault conditions of the machine fieldbus controller.

**9.4 Possible combined options: /IQ, /IZ**

## 10 ELECTRONIC CONNECTIONS

### 10.1 Main connector signals - 7 pin - standard and /Q option - RZMO-AEB and RZMO-AES (A1)

PIN	Standard	/Q	TECHNICAL SPECIFICATIONS	NOTES
A	V+		Power supply 24 Vdc	Input - power supply
B	V0		Power supply 0 Vdc	Gnd - power supply
C	AGND		Analog ground	Gnd - analog signal
		ENABLE	Enable (24 Vdc) or disable (0 Vdc) the driver, referred to V0	Input - on/off signal
D	INPUT+		Pressure reference input signal: $\pm 10$ Vdc / $\pm 20$ mA maximum range Defaults are 0 $\div$ 10 Vdc for standard and 4 $\div$ 20 mA for /I option	Input - analog signal <b>Software selectable</b>
E	INPUT-		Negative reference input signal for P_INPUT+	Input - analog signal
F	MONITOR referred to: AGND	V0	Pressure monitor output signal: $\pm 5$ Vdc maximum range Default is 0 $\div$ 5 Vdc (1V = 1A)	Output - analog signal <b>Software selectable</b>
G	EARTH		Internally connected to driver housing	

### 10.2 Main connector signals - 12 pin - /Z option - RZMO-AEB and RZMO-AES (A2)

PIN	/Z	TECHNICAL SPECIFICATIONS	NOTES
1	V+	Power supply 24 Vdc	Input - power supply
2	V0	Power supply 0 Vdc	Gnd - power supply
3	ENABLE	Enable (24 Vdc) or disable (0 Vdc) the driver, referred to V0	Input - on/off signal
4	INPUT+	Pressure reference input signal: $\pm 10$ Vdc / $\pm 20$ mA maximum range Defaults are 0 $\div$ 10 Vdc for standard and 4 $\div$ 20 mA for /I option	Input - analog signal <b>Software selectable</b>
5	INPUT-	Negative reference input signal for P_INPUT+	Input - analog signal
6	MONITOR	Pressure monitor output signal: $\pm 5$ Vdc maximum range Defaults is 0 $\div$ 5 Vdc (1V = 1A)	Output - analog signal <b>Software selectable</b>
7	NC	Do not connect	
8	NC	Do not connect	
9	VL+	Power supply 24 Vdc for driver's logic and communication	Input - power supply
10	VLO	Power supply 0 Vdc for driver's logic and communication	Gnd - power supply
11	FAULT	Fault (0 Vdc) or normal working (24 Vdc), referred to V0	Output - on/off signal
PE	EARTH	Internally connected to driver housing	

### 10.3 Communication connectors - RZMO-AEB (B) and RZMO-AES (B) (C)

(B) USB connector - M12 - 5 pin always present		
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)
1	+5V_USB	Power supply
2	ID	Identification
3	GND_USB	Signal zero data line
4	D-	Data line -
5	D+	Data line +

(C1) BC fieldbus execution, connector - M12 - 5 pin (2)		
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)
1	CAN_SHLD	Shield
2	NC	do not connect
3	CAN_GND	Signal zero data line
4	CAN_H	Bus line (high)
5	CAN_L	Bus line (low)

(C2) BP fieldbus execution, connector - M12 - 5 pin (2)		
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)
1	+5V	Termination supply signal
2	LINE-A	Bus line (high)
3	DGND	Data line and termination signal zero
4	LINE-B	Bus line (low)
5	SHIELD	

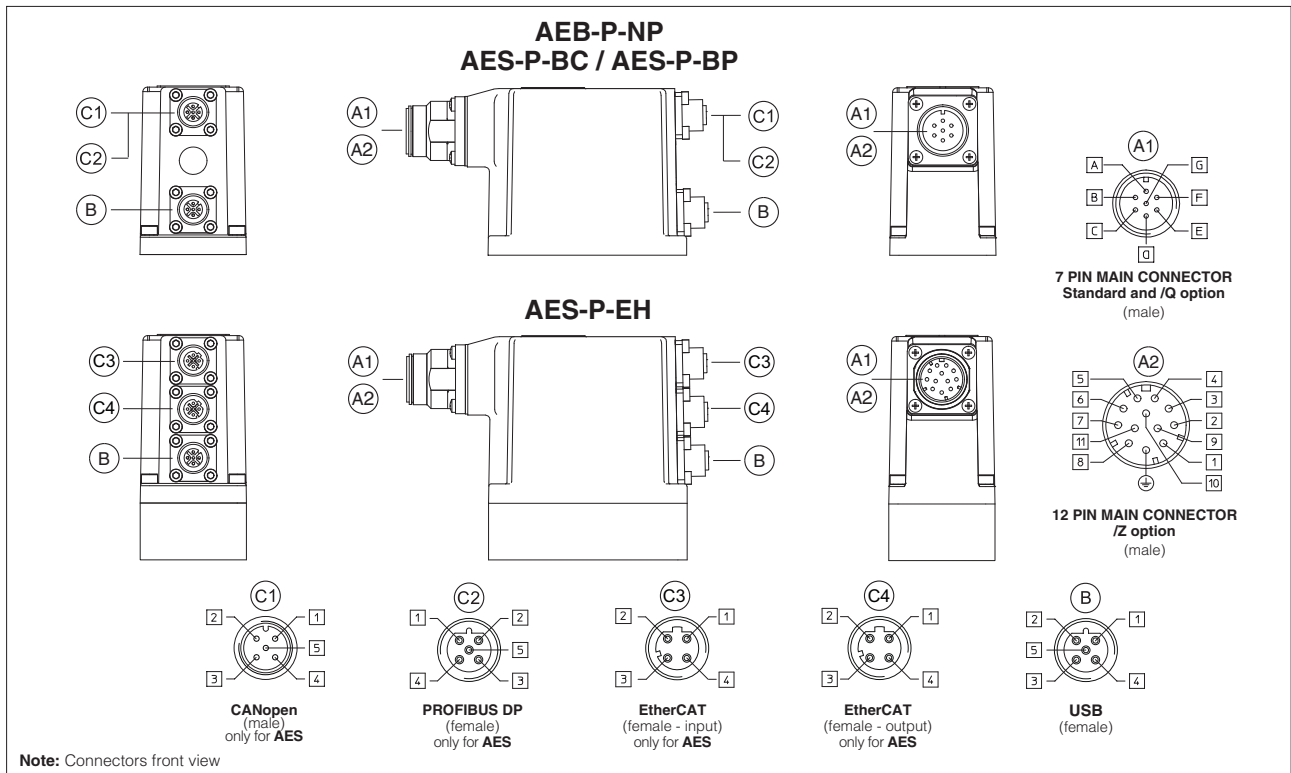
(C3) (C4) EH fieldbus execution, connector - M12 - 4 pin (2)		
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)
1	TX+	Transmitter
2	RX+	Receiver
3	TX-	Transmitter
4	RX-	Receiver
Housing	SHIELD	

Notes: (1) shield connection on connector's housing is recommended (2) only for AES execution

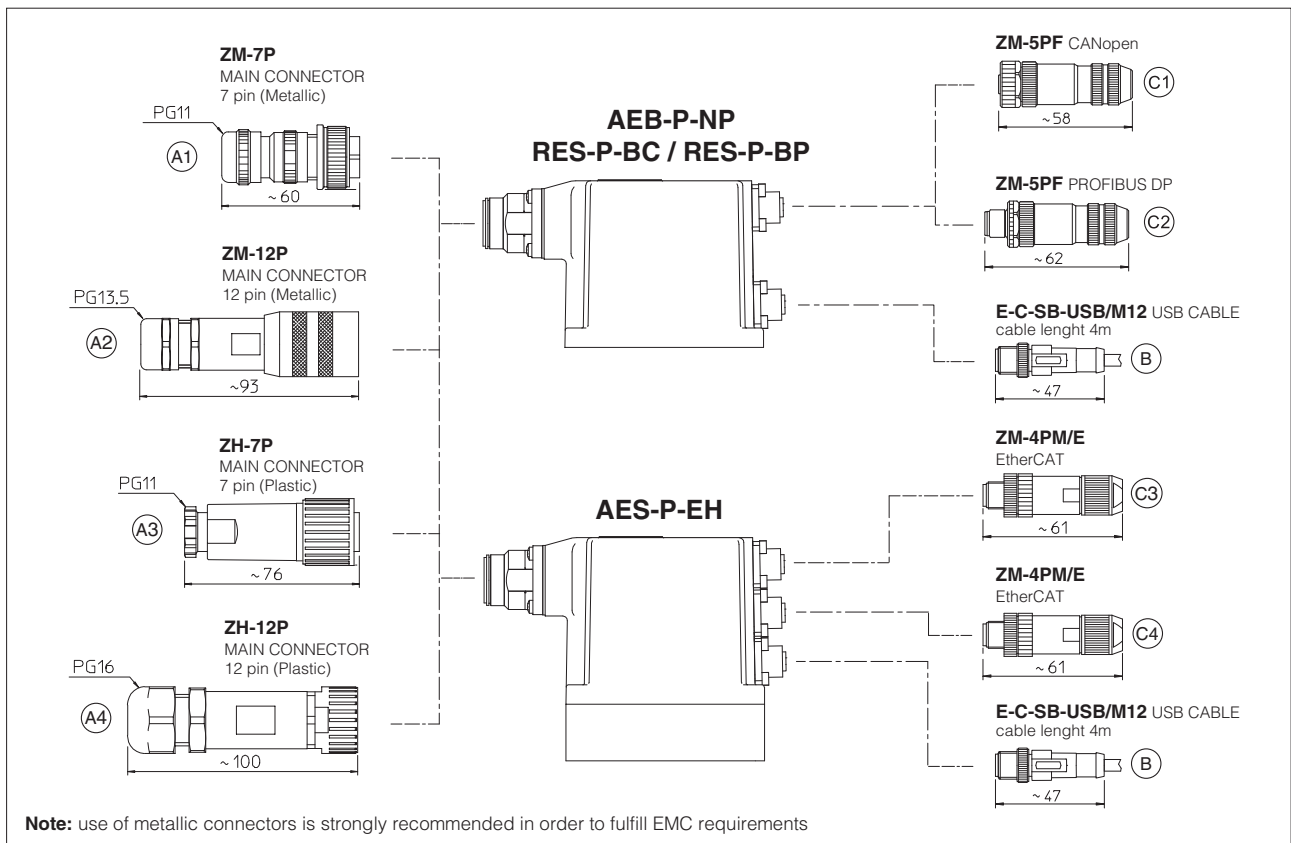
### 10.4 Solenoid connection - only for RZMO-A

PIN	SIGNAL	TECHNICAL SPECIFICATION	Connector code 666
1	COIL	Power supply	
2	COIL	Power supply	
3	GND	Ground	

10.5 Connections layout - only for AEB and AES



11 CONNECTORS



12 MODEL CODES OF MAIN CONNECTORS AND COMMUNICATION CONNECTORS - to be ordered separately

VALVE VERSION	A (1) Power supply	AEB AES	AEB/Z AES/Z	BC - CANopen	BP - PROFIBUS DP	EH - EtherCAT
CONNECTOR CODE	666	ZM-7P (A1)	ZM-12P (A2)	ZM-5PF (C1)	ZM-5PF/BP (C2)	ZM-4PM/E (C3)
		ZH-7P (A3)	ZH-12P (A4)			ZM-4PME (C4)
PROTECTION DEGREE	IP65	IP67				
DATA SHEET	K500	GS115, K500				

(1) Connectors supplied with the valve

only for AES

**13 PROGRAMMING TOOLS** - see tech table **GS500**

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver. For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options:

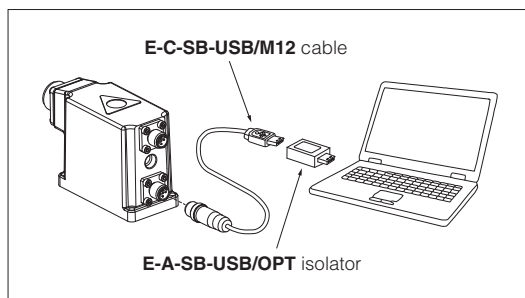
**E-SW-BASIC** support: NP (USB) PS (Serial) IR (Infrared)  
**E-SW-FIELDBUS** support: BC (CANopen) BP (PROFIBUS DP) EH (EtherCAT)  
 EW (POWERLINK)

**E-SW-\*/PQ** support: valves with SP, SF, SL alternated control (e.g. E-SW-BASIC/PQ)

**WARNING: drivers USB port is not isolated!**

The use of isolator adapter is highly recommended for PC protection (see table **GS500**)

**USB connection**

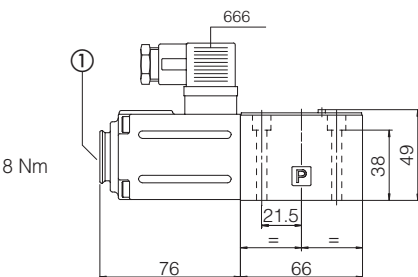


**14 INSTALLATION DIMENSIONS [mm]**

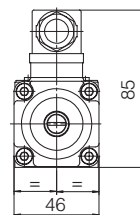
**ISO 4401: 2005**

**Mounting surface:**  
**4401-03-02-0-05** (see table P005)  
 (without ports A and B)

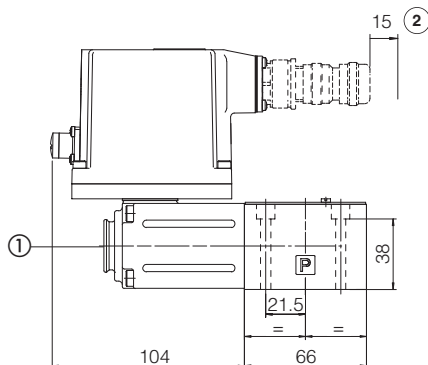
Fastening bolts:  
 4 socket head screws  
 M5X50 class 12.9 Tightening torque = 8 Nm  
 Seals: 2 OR 108  
 Ports P, T: Ø = 5 mm



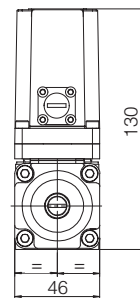
**RZMO-A**



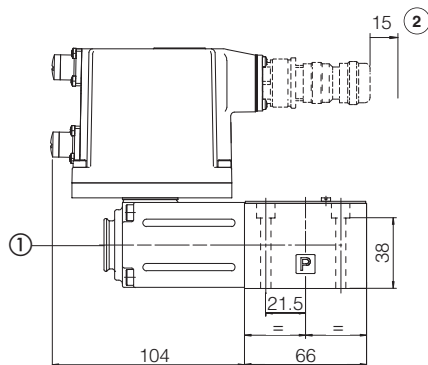
Mass: 1,8 Kg



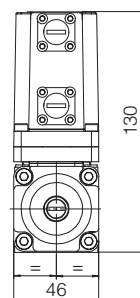
**RZMO-AEB**



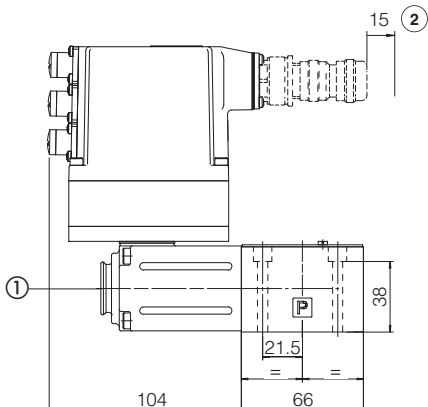
Mass: 2,7 Kg



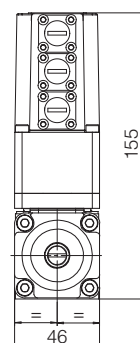
**RZMO-AES-BP**  
**RZMO-AES-BC**



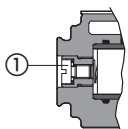
Mass: 2,7 Kg



**RZMO-AES-EH**



Mass: 2,8 Kg



- ① = Screw for air bleeding: at the first valve commissioning the air eventually trapped inside the solenoid must be bled-off though the screw ①
- ② = Space to remove the 7 or 12 pin main connector. For main and communication connectors see section 11, 12